

ENROLMENT OF EM2040

at the Norwegian Hydrographic Service

Presented by Harald Sæther



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- Presentation by Harald Sæther
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 - employee of Geograf AS
 - Surveyor and data processor since 2004
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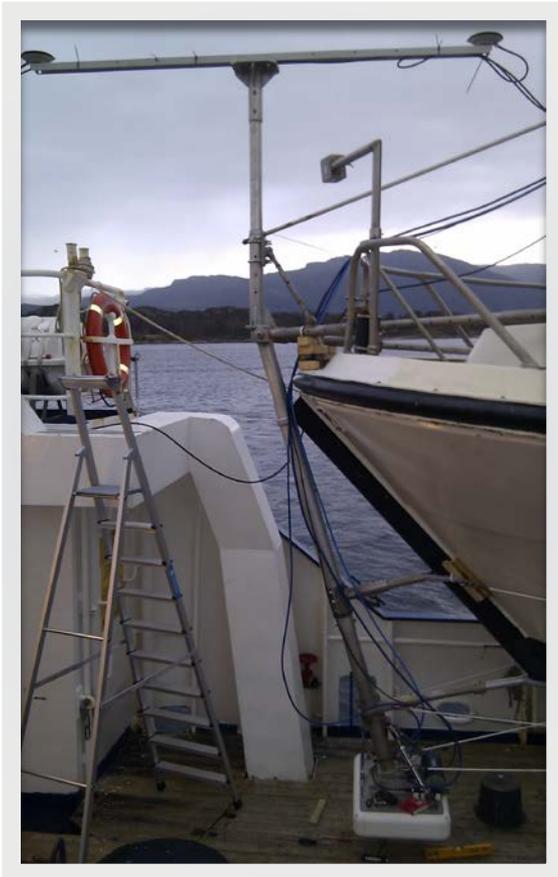
Enrolment of EM2040

- At the end of 2012 the Norwegian Hydrographic Services purchased two sets of EM2040 Dual Heads
- They will be installed on two new launching vessels, expected to be delivered the fall of 2013
- In addition there will be a third vessel operated by NHS, but owned by the Norwegian Coastal Administration (Kystverket).

Trials EM2040

- Prior to the purchase, in October 2011, Kongsberg allowed NHS to test EM2040 on one of our own vessels.
- The test area was just outside Florø, where the bathymetry is very rough, and where NHS had previously experienced a lot of poor quality data due to the shape of the seabed.

Installation EM2040



- Mounted on the bow of Sjøtroll, october 2011.



Execution

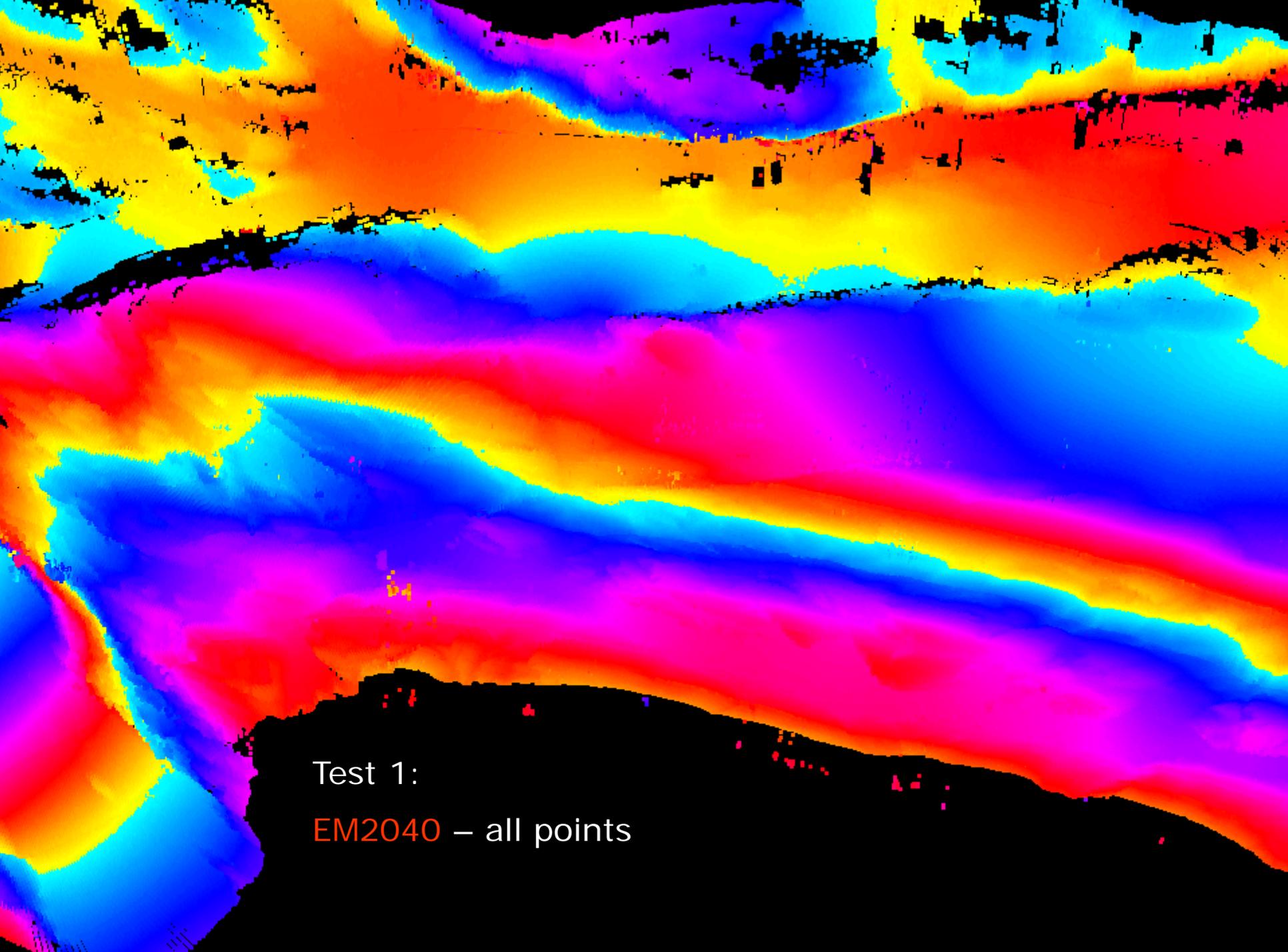
- The idea was to compare data from the EM2040 with data from the already installed EM3002 Dual head system.
- The trials for EM2040 were performed several times on different locations...
- and were repeated the next day using EM3002D

The study

- Each survey consisted of 5-6 surveylines and of about 5 minutes of logging for each line.
- Neptune was used as the software for post-processing

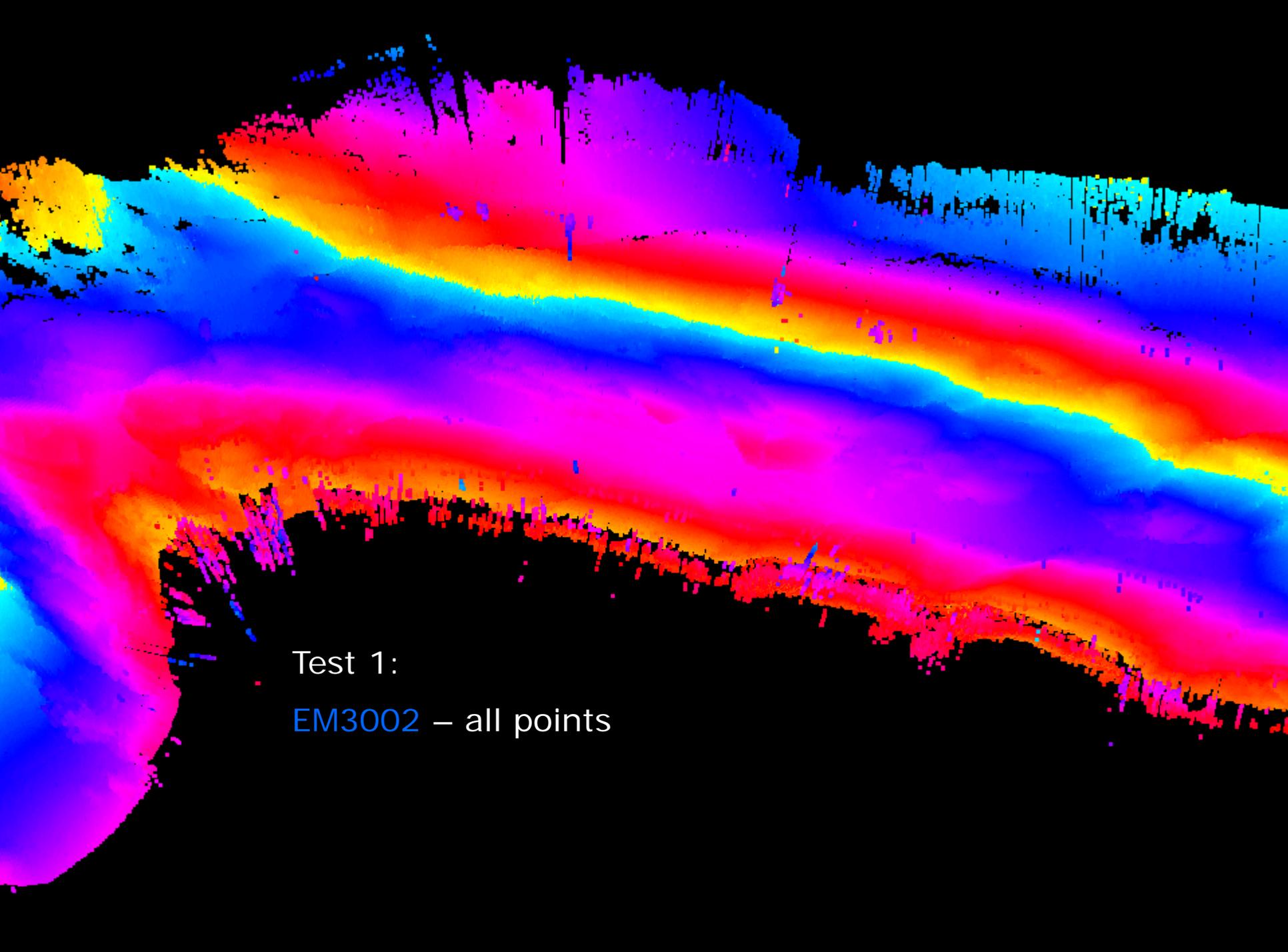
The answers we searched:

- Did the data look any better than EM3002?
- And how would this effect us in the post-processing?
Would we spend even more time processing?
- The data was compared by completely processing both datasets



Test 1:

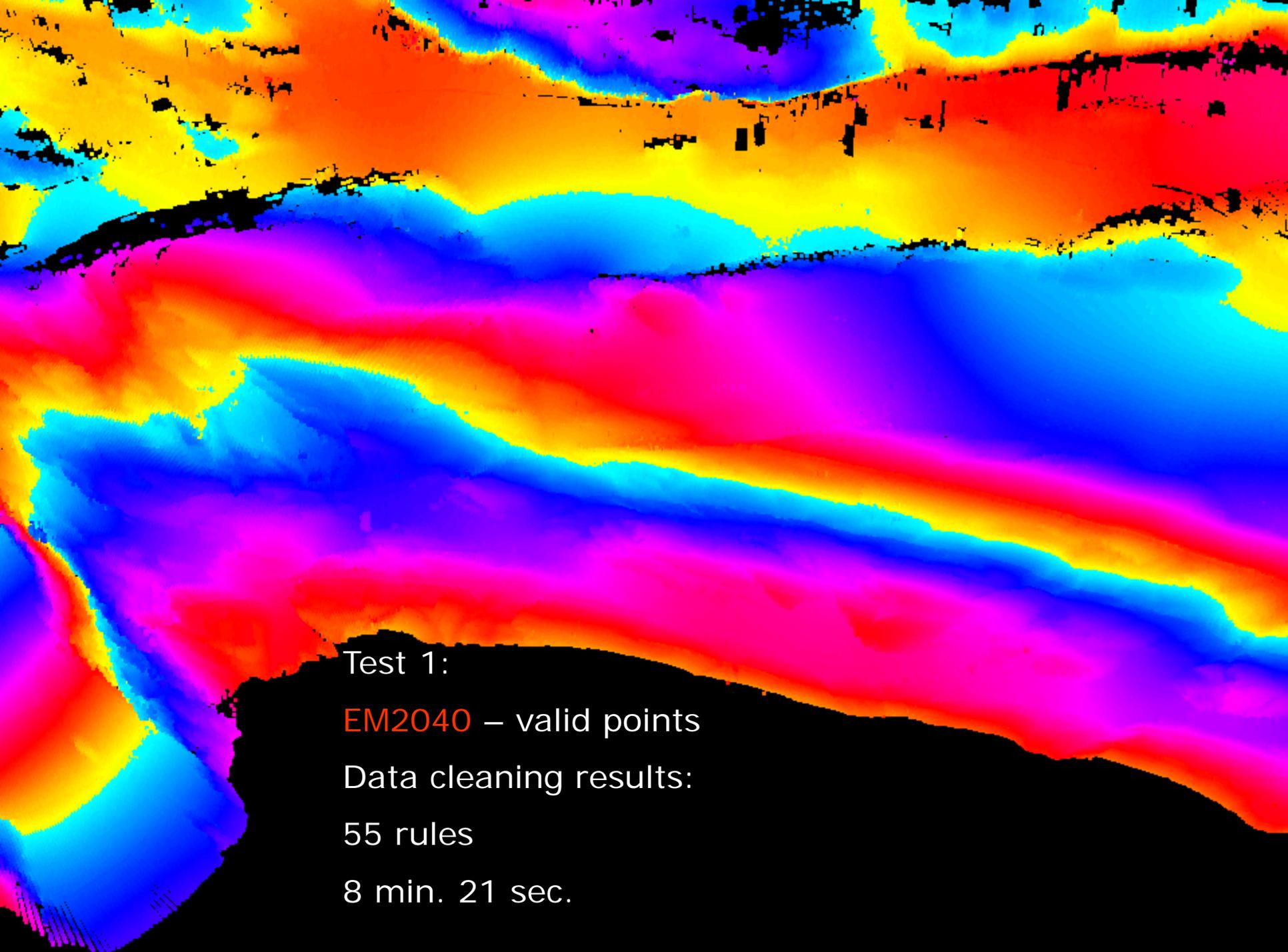
EM2040 – all points



Test 1:
EM3002 – all points

Did you notice any differences?

- If not, go back...
- Nothing has been cleaned at this point.
- But after cleaning both sets (EM2040 and EM3002), it looked like this:



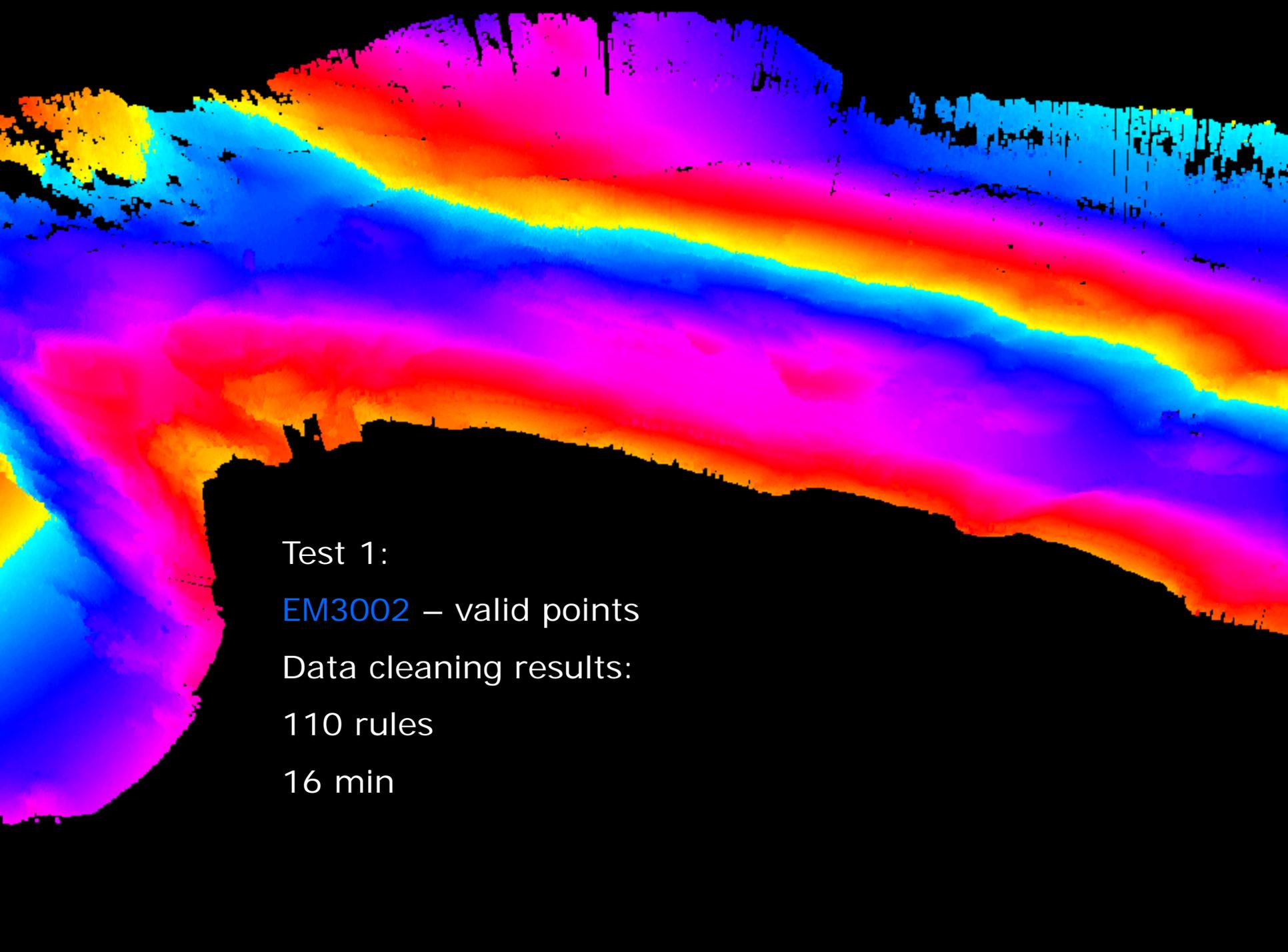
Test 1:

EM2040 – valid points

Data cleaning results:

55 rules

8 min. 21 sec.



Test 1:

EM3002 – valid points

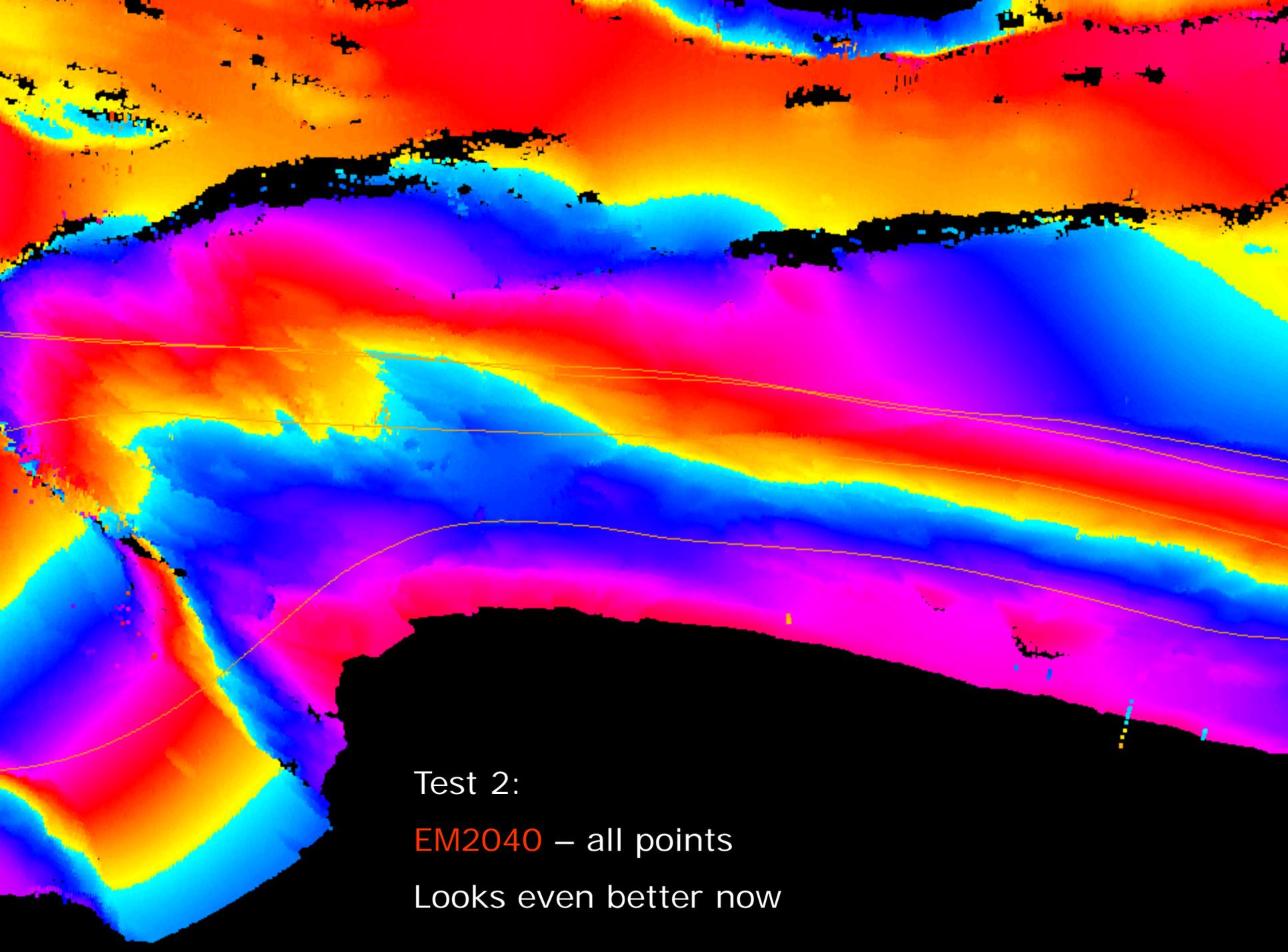
Data cleaning results:

110 rules

16 min

Test 2

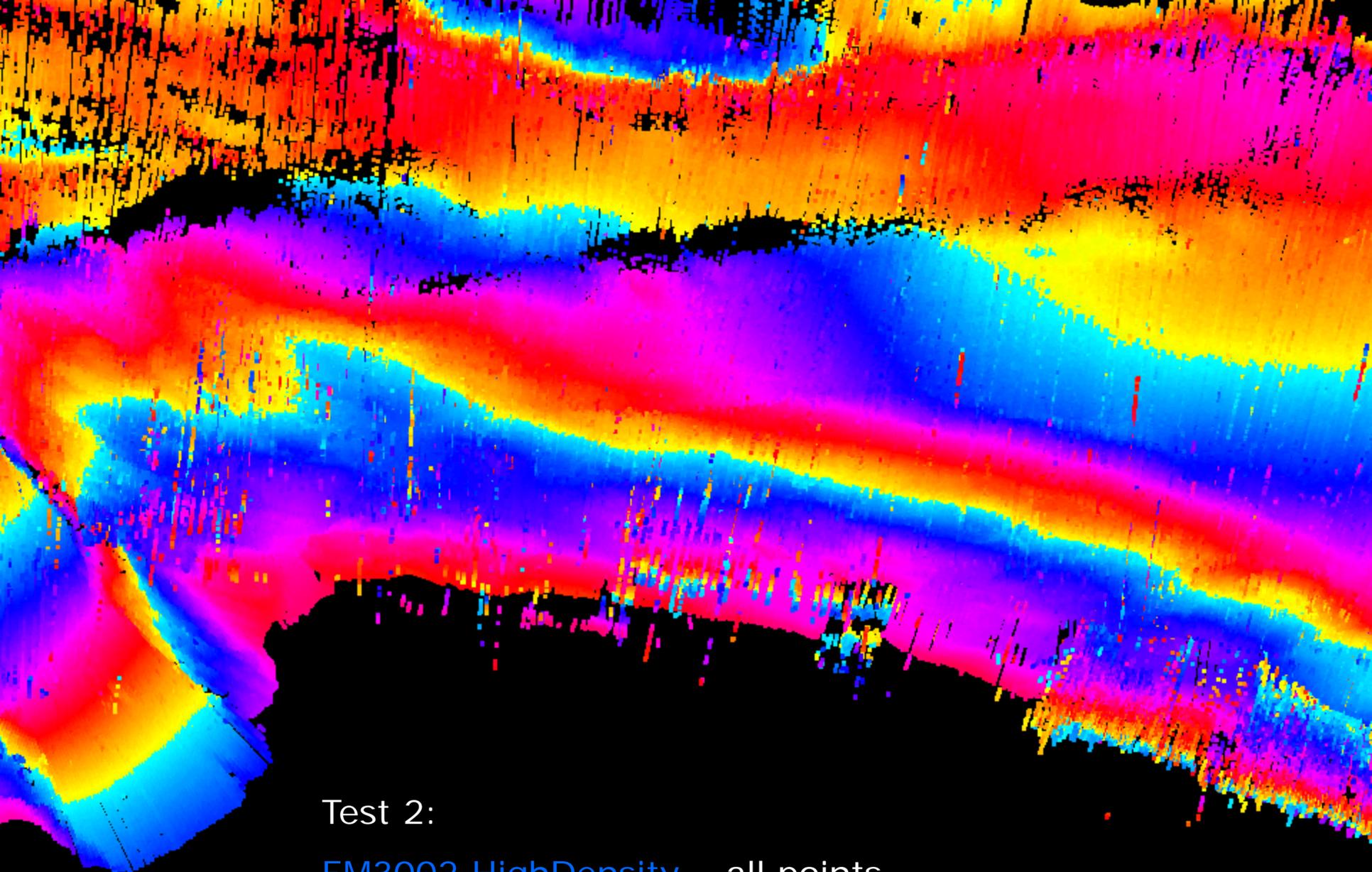
- Of course we had to repeat the test with another survey



Test 2:

EM2040 – all points

Looks even better now

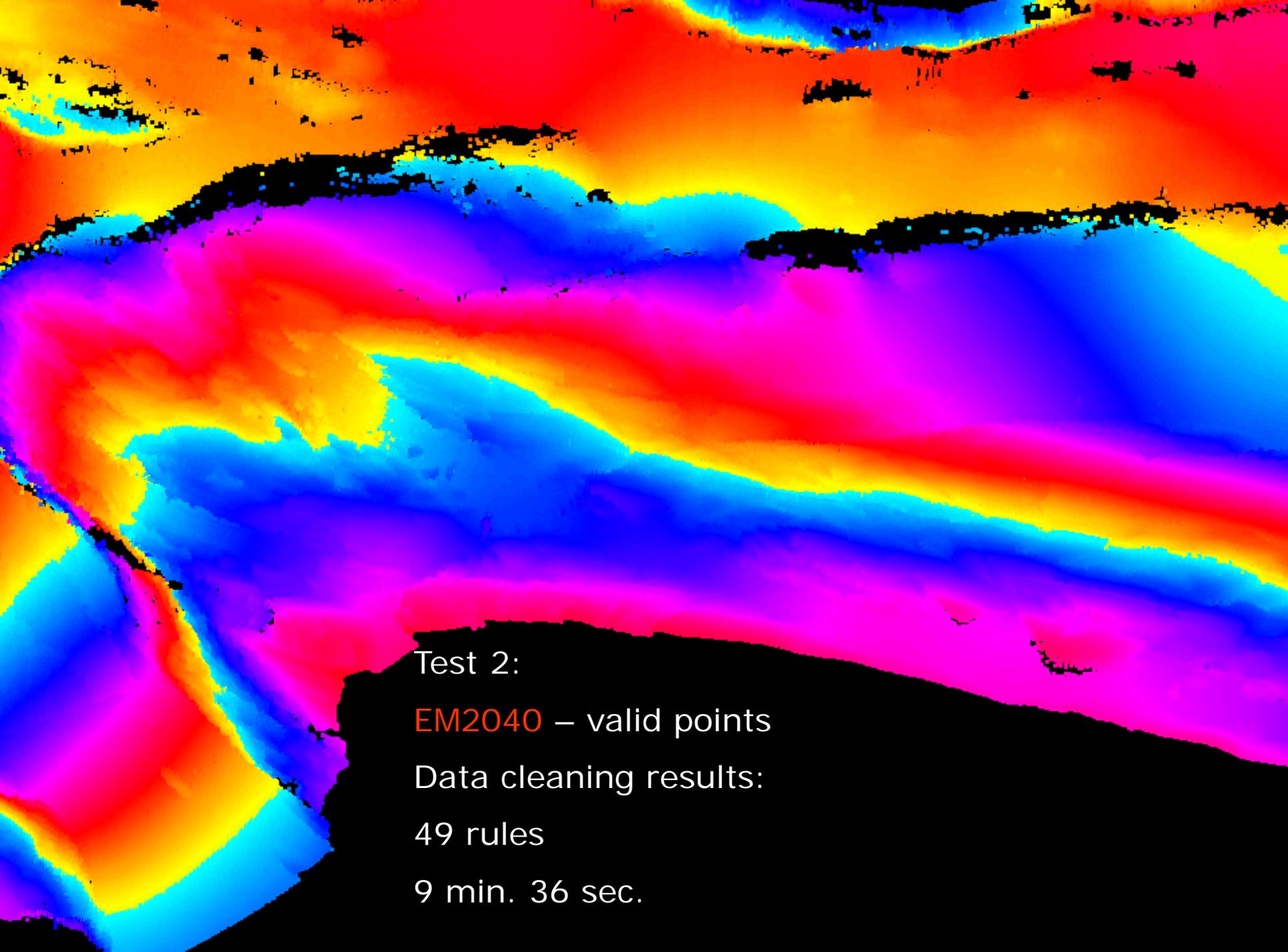


Test 2:

EM3002 HighDensity – all points

You saw the difference this time

- I know you did
- Like any decent data processor I still had to clean the data, and this time the results were:



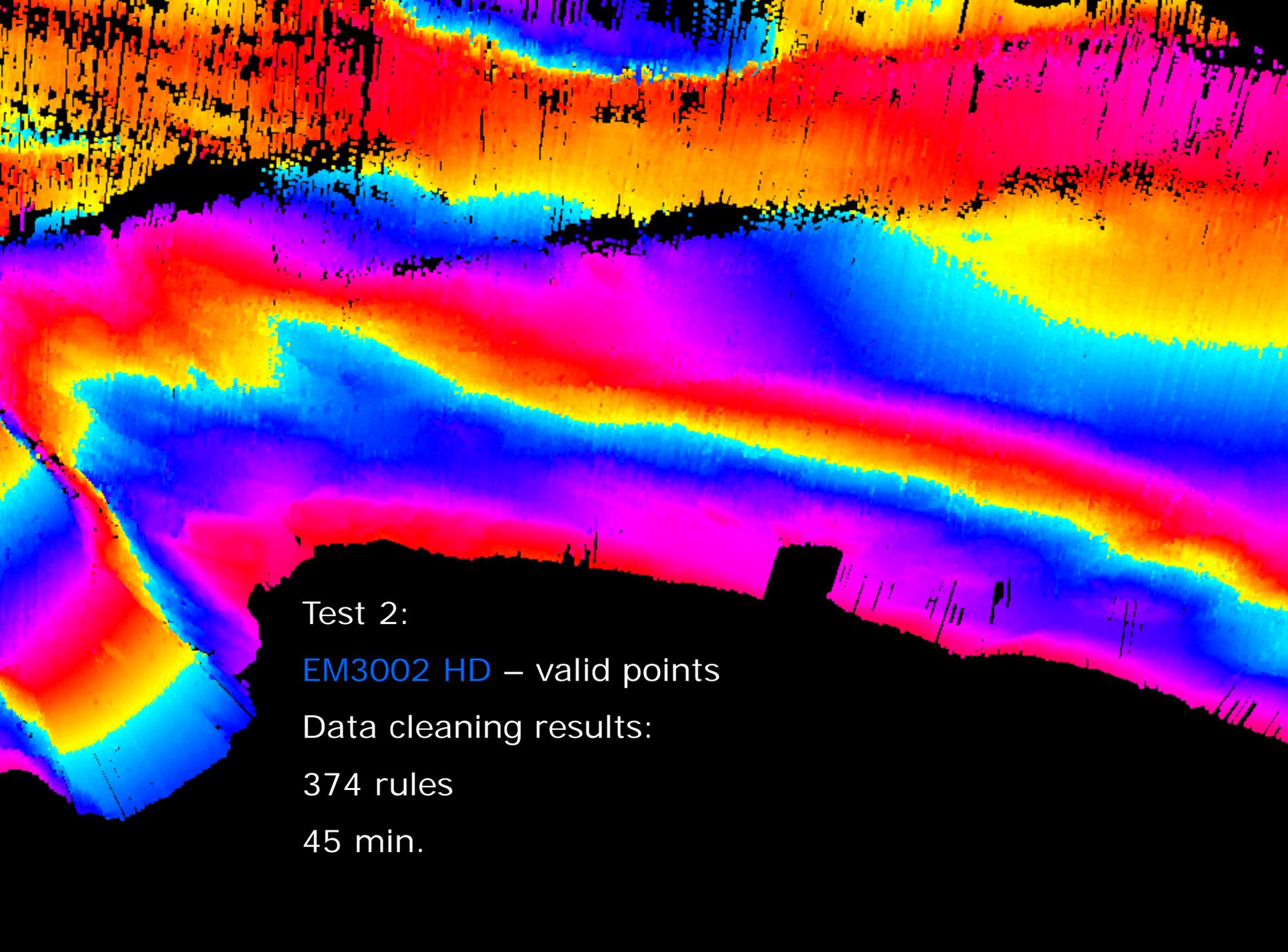
Test 2:

EM2040 – valid points

Data cleaning results:

49 rules

9 min. 36 sec.



Test 2:

EM3002 HD – valid points

Data cleaning results:

374 rules

45 min.

Test 1

| | Rejected Points | Accepted Points |
|--------|-----------------|-----------------|
| EM3002 | 109 221 (4,6%) | 2 269 445 |
| EM2040 | 33 151 (0,9%) | 3 568 743 |

Test 2

| | Rejected Points | Accepted Points |
|--------------|-----------------|-----------------|
| EM3002 HD | 233 130(7,3%) | 2 950 715 |
| EM2040 | 63 256 (1,5%) | 4 080 211 |

Summary of data cleaning

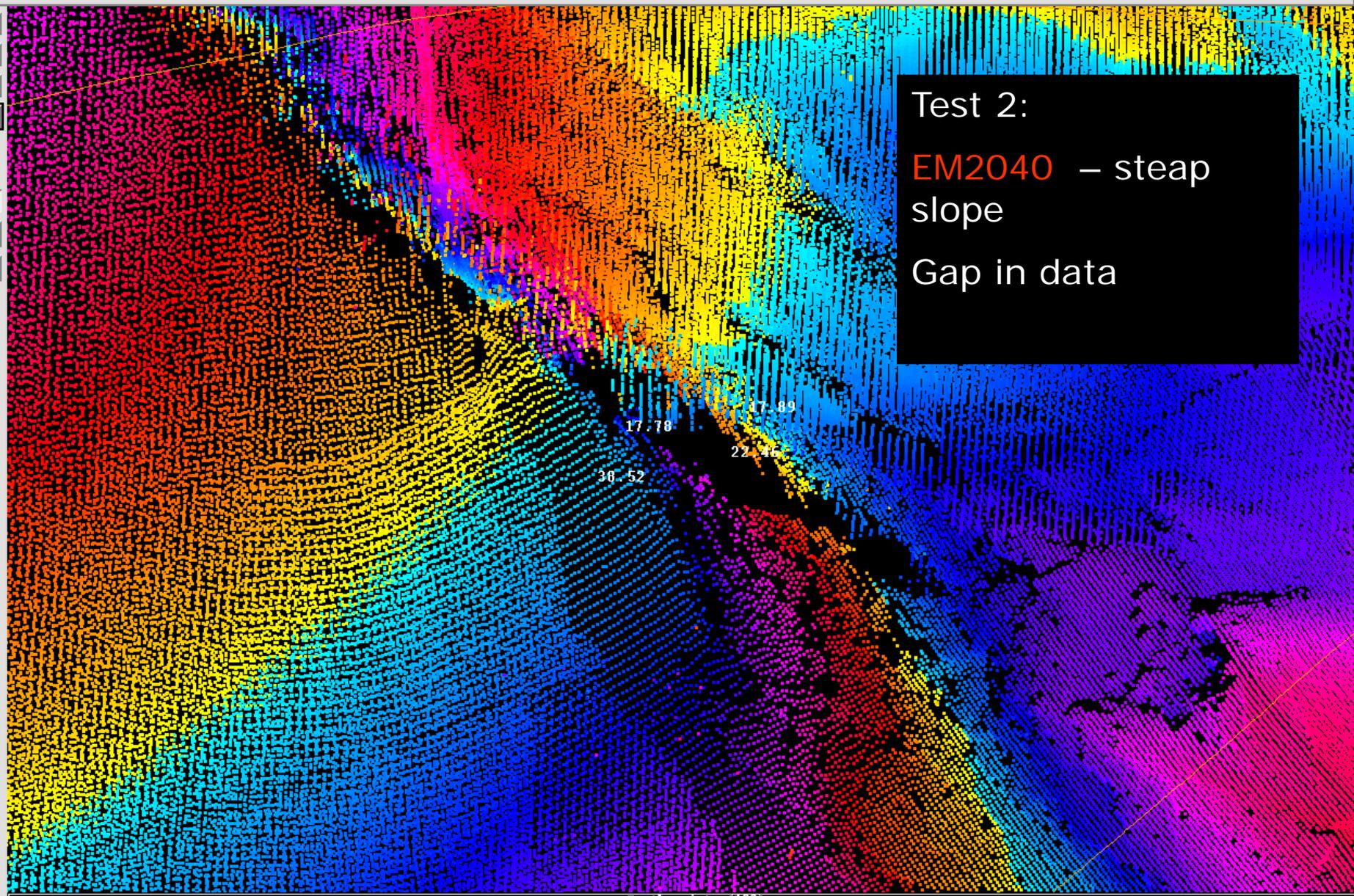
| | Time Test 1 | Time Test 2 | # rules Test 1 | # rules Test 2 | % rejected points Test 1 | % rejected points Test 2 |
|---------|----------------|----------------|-------------------|-------------------|-----------------------------------|-----------------------------------|
| EM3002D | 16 min | 45 min | 110 | 374 | 4,6 % | 7,3 % |
| EM2040 | 8,3 min | 9,5 min | 55 | 49 | 0,9 % | 1,5 % |

Discussions

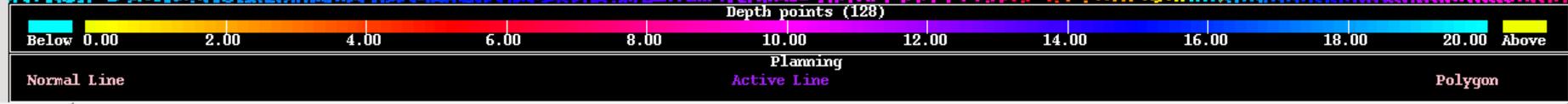
Observations from the data

- U
- R
- Z
- Z
- ◆ +1
- ▽ *2
- G
- ?
-

Test 2:
 EM2040 – steep
 slope
 Gap in data

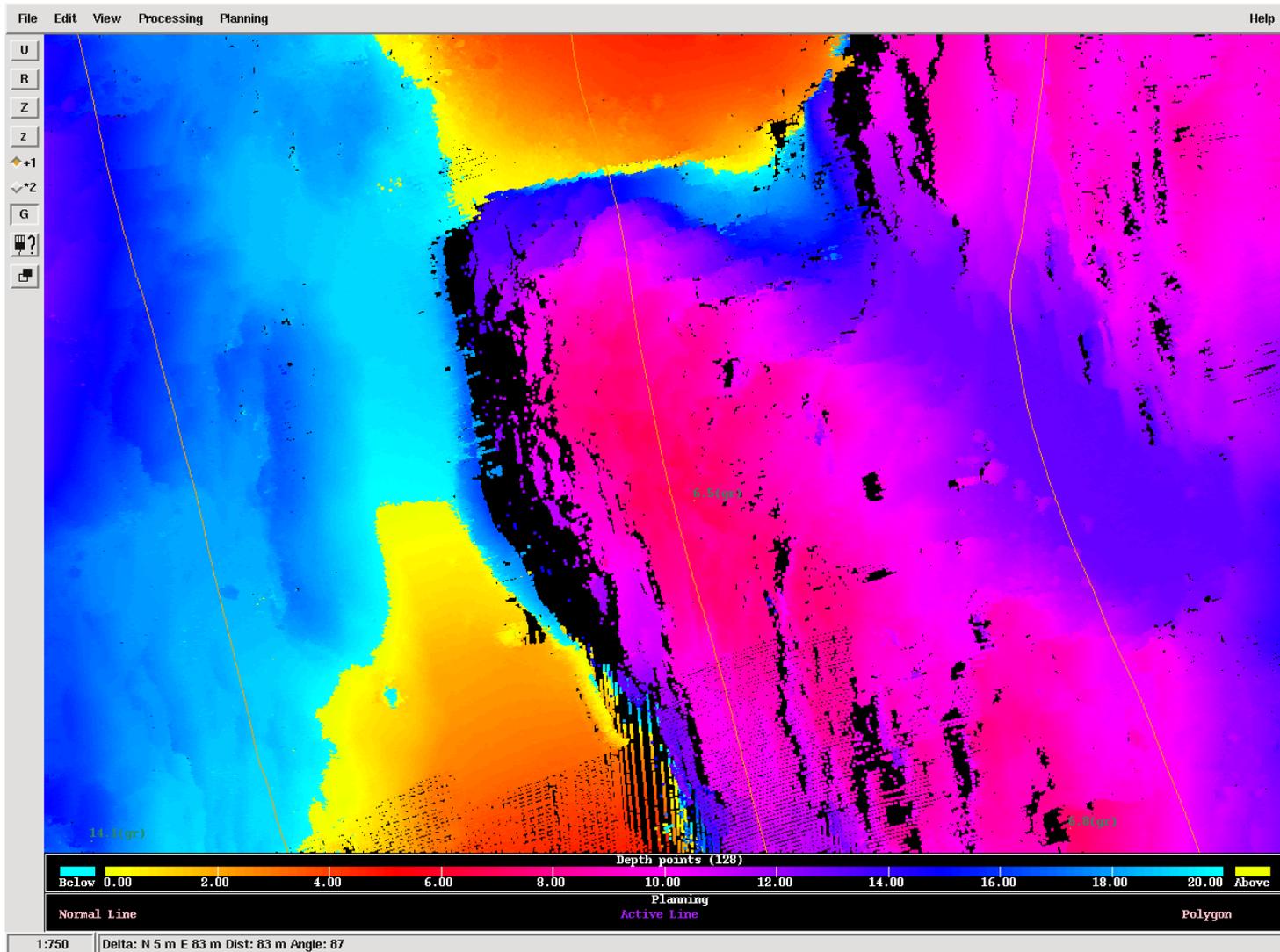


17.78
 17.89
 22.46
 30.52



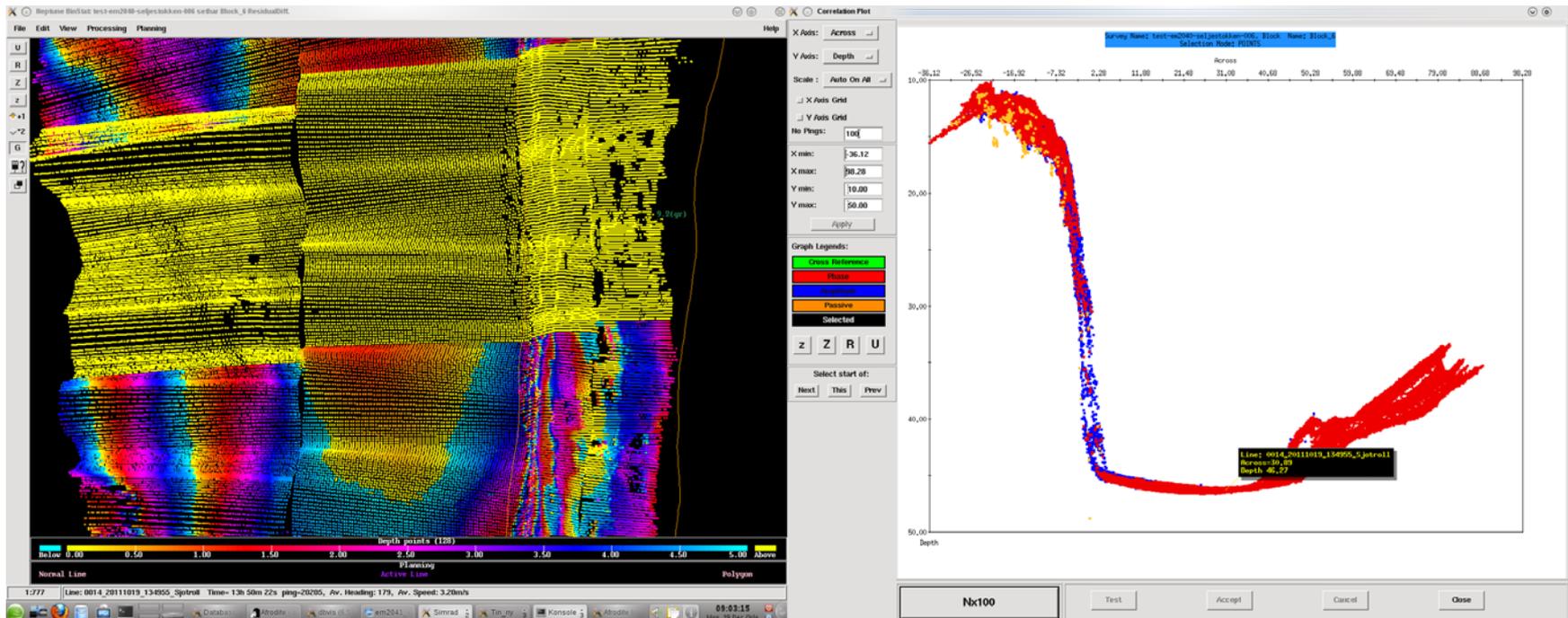
These gaps appeared more often at slopes and were larger than we had seen before.

Could it be due to certain filtersettings in SIS?



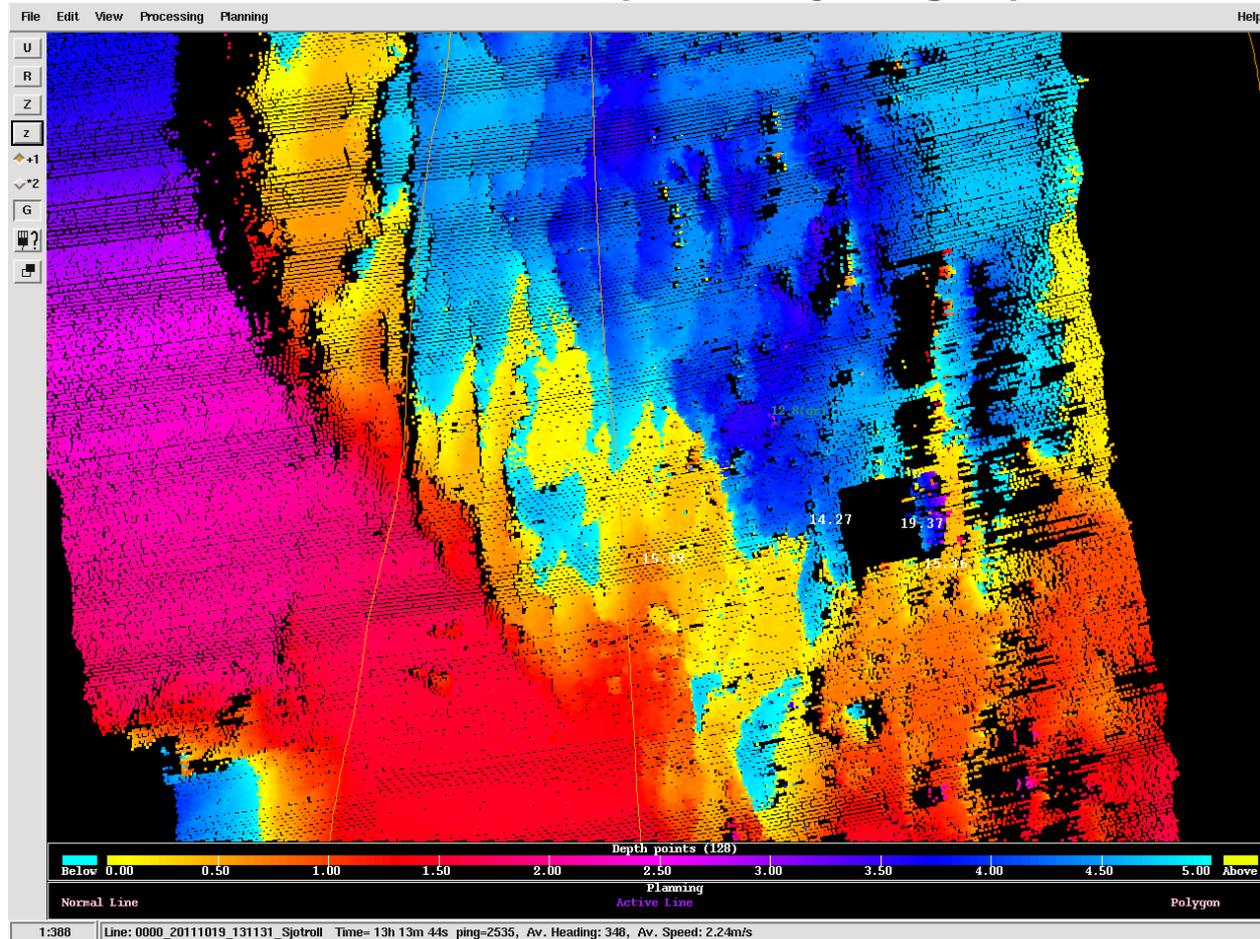
Optimal angle

Very good detection of the steep slope with perfect angle.

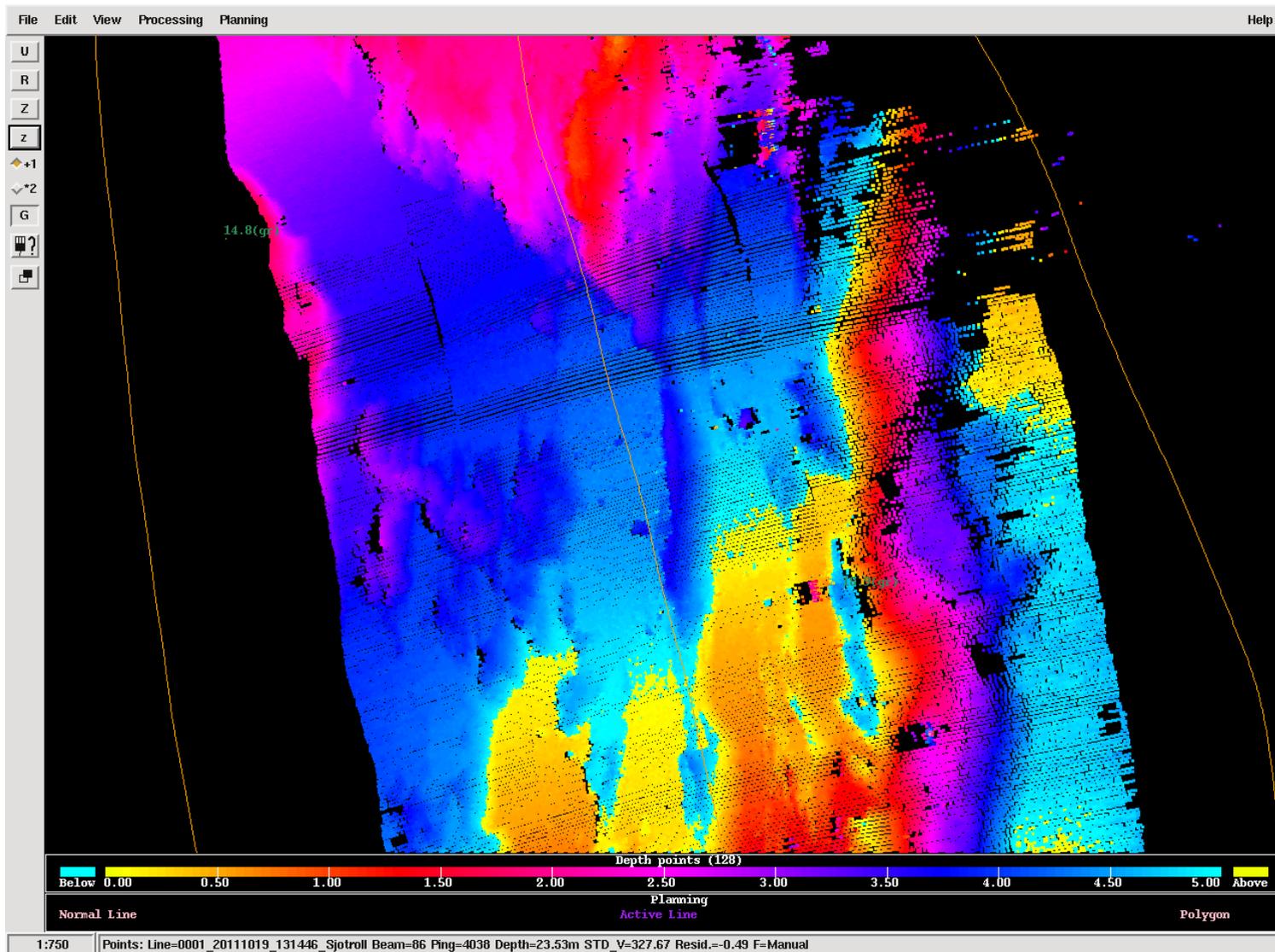


Sink holes?

Many false sink holes appeared more often than we have been used to, particularly along slopes.

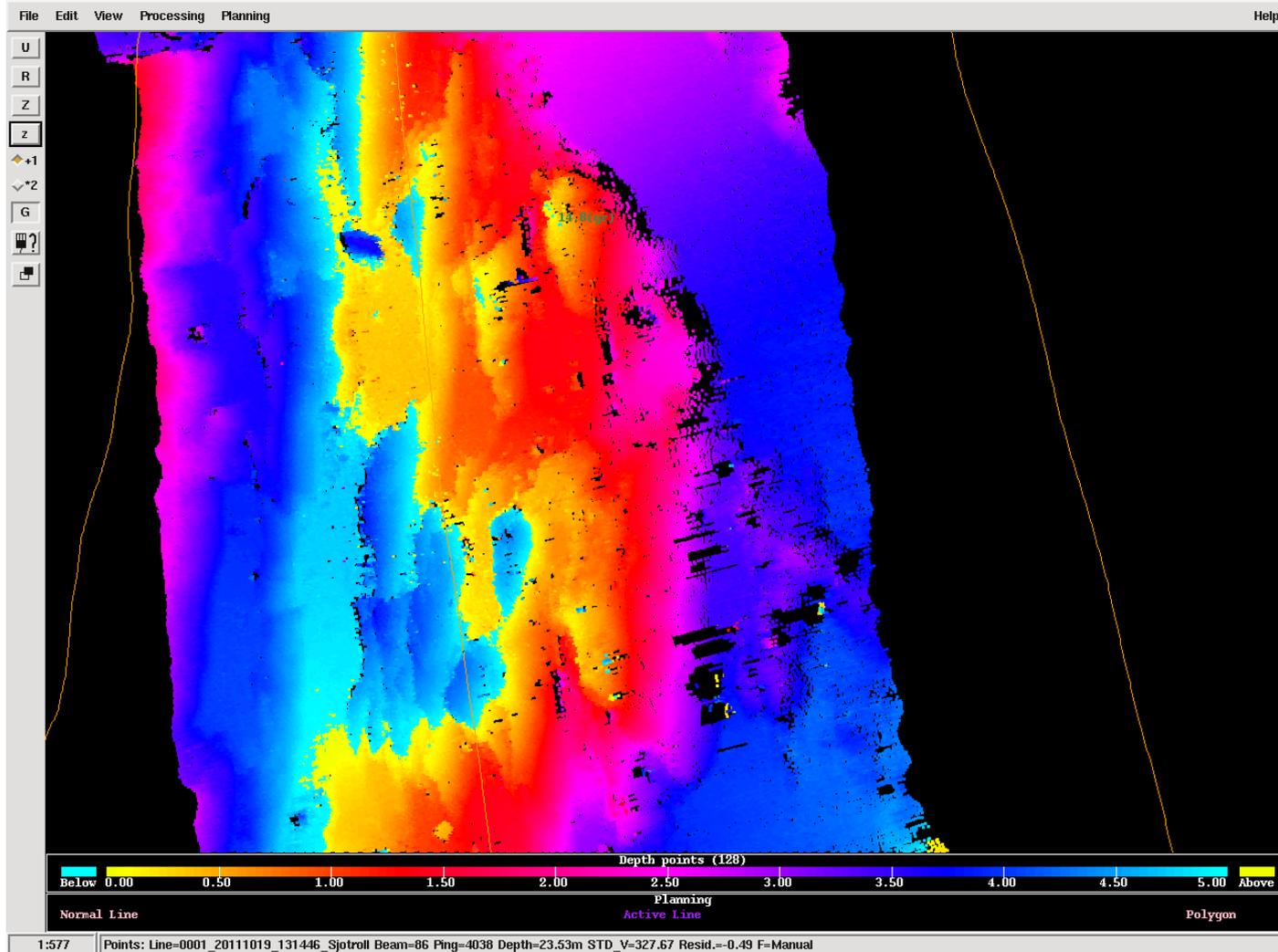


All points
Some noise and gaps during bad weather (high
pitching)



EM2040

All points (nothing cleaned)



Considerations

- The number of re-runs (lines to fill in the gaps) were less than before, but not by much.
- We think that this would have been better for EM2040 during more normal pitching.
- Apart from the pitching, the positioning of the sonar (bow-mounted) might also have been an advantage for EM2040, since bubbles occur a lot more further down the hull of the vessel, which is a problem for the hull-mounted EM3002, during rough seas.
- All the tests were also repeated by another data processor with minor variations.

Thank you for your attention

| | Time Test 1 | Time Test 2 | # rules Test 1 | # rules Test 2 | % rejected points Test 1 | % rejected points Test 2 |
|---------|----------------|----------------|-------------------|-------------------|-----------------------------------|-----------------------------------|
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